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This textbook presents a systematic study of the qualitative and geometric theory of nonlinear differential equations and dynamical systems. Although the main topic of the book is the local and global behavior of nonlinear systems and their bifurcations, a thorough treatment of linear systems is given at the beginning of the text.

Differential Equations and Dynamical Systems | Lawrence ...

For $x_p = e^{-t}$, $x' = -e^{-t}$, $x' = e^{-t}$. So $x' - 3x' + 2x_p = e^{-t} + 3e^{-t} + 2e^{-t} = 6e^{-t} = r.h.s.$ The general solution is thus

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$x = c_1 e^t + c_2 e^{2t} + e^{-t}$. (b) Using the initial conditions $x(0) = 4$, $x'(0) = 3$ for the first solution we get, $4 = c_1 + c_2 + 2$ and $3 = c_1 + 2c_2$. Solving these equations for c_1 and c_2 we have $c_1 = c_2 = 1$.

Solutions Manual Introduction Differential

$x^3 = 2 \sin x$ $x^1 = 2 \cos x$ C^3 4
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 $x^1 = 2 \cos x$ $C^4 x^C$ x^2 . 1 4 $.4 x^C 8/D$
 $4 x^3 C 8 x^2 C$ $3 x^2$. $1.2.4$. (a) If $y(0) = x e^x$,
then $y'(x) = x e^x + e^x = e^x(x+1)$. x/e^x , and
 $y(0) = 1$ $1) 1D 1C$, so $c_D = 0$ and $y_D = 1/x/e^x$.

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This solutions manual is a guide for instructor's using A Course in Ordinary Differential Equations. Many problems have their solution presented in its entirety while some merely have an

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answer and few are skipped. This should provide sufficient guidance through the problems posed in the text.

Solutions Manual for A Course in Ordinary Differential ...

reads $r(0) = h$, $r'(0) = 0$. The equation of motion reads $r = M(R+r)^2$ (exact model) respectively $r = g$ (approximate model); where $g = M/R^2$ and R, M are the radius, mass of the earth, respectively. (i) Transform both equations into a first-order system. (ii) Compute the solution to the approximate system corresponding to the given initial condition.

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