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1.2. Linear Programming: A Graphical Perspective in \mathbb{R}^2 13 The feasible region is shown in Figure 1.4. The LP has alternative optimal solutions that fall on the segment connecting $x = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ to $x = \begin{pmatrix} 6 \\ 0 \end{pmatrix}$. Each such solution has an objective value of $z = 12$, and the parametric representation of the segment is given by $x = \begin{pmatrix} 3t+6(1-t) \\ t+0(1-t) \end{pmatrix}$...

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2.2Fixed Points and Stability Analyze the following equations graphically. In each case, sketch the vector field on the real line, find all the fixed points, classify their stability, and sketch the graph of $x(t)$. 2.2.1 $x' = 4x^2 - 16$ Theanalyticalsolutionis:

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Nonlinear Programming 13 Numerous mathematical-programming applications, including many introduced in previous chapters, are cast naturally as linear programs. Linear programming assumptions or approximations may also lead to appropriate problem representations over the range of decision variables being considered. At other times,

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